

ICCM20

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Multifunctional Skin Material for Morphing Leading Edge Applications

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Anton Rudenko

AFOSR Workshop on "Active Composites for Morphing Structures"

21. July 2015

Copenhagen, Denmark



Knowledge for Tomorrow



Overview

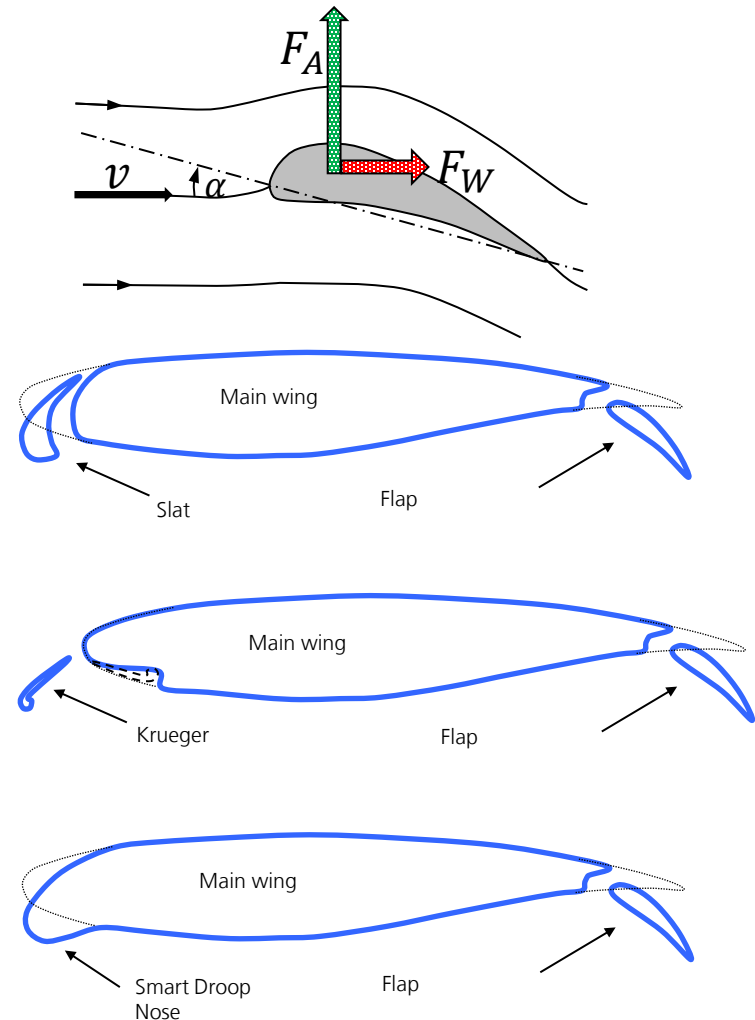
- Motivation & Challenges for morphing leading edge
 - Laminarity
 - Large scale morphing
 - 3D morphing
 - „The real world“
- Approaches for kinematics and compliant mechanisms
 - Kinematics design
 - Flexural joints
 - Compliant mechanisms design
- Approaches for skin design
 - GFRP 3D
 - GFRP-EPDM
 - GFRP with integrated layers
 - Polyurethan with foam



Motivation & Challenges for morphing leading edge

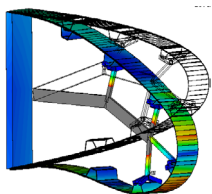
Laminarity

- High-Lift devices on leading and trailing edge for lift generation at low speed (take-off & landing)
 - Common high-lift devices (Slat, Krueger) are highly effective ($c_{a,max}$) but exhibit slots, gaps and steps
- Transition to turbulent flow on main wing due to steps and gaps
- Drag due to steps and gaps
- Primary source of airframe noise in approach/landing



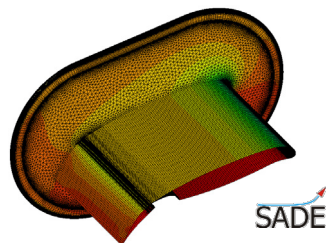
Motivation & Challenges for morphing leading edge

History of Smart Droop Nose Development at the DLR



SmartLED
2007-2010

*Ground Demonstrator, 3D,
Feasibility*



SADE
2008-2012

*Wind Tunnel Model, 2D,
Shape Control*

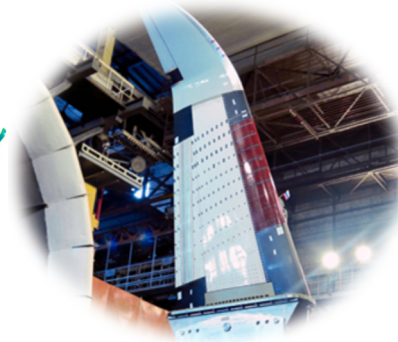


JTI-SFWA
2009-2013

*Ground Demonstrator, 2D,
Kinematics, Fatigue*



Hochauftrieb
künftiger Verkehrsflugzeuge



SARISTU
2011-2015

*Wind Tunnel Model, 3D,
Integration of Functionalities &
Shape Control & Kinematics*



Motivation & Challenges for morphing leading edge

Large Scale Morphing

- SFB880: national special research program for the development of upstream High Lift technologies

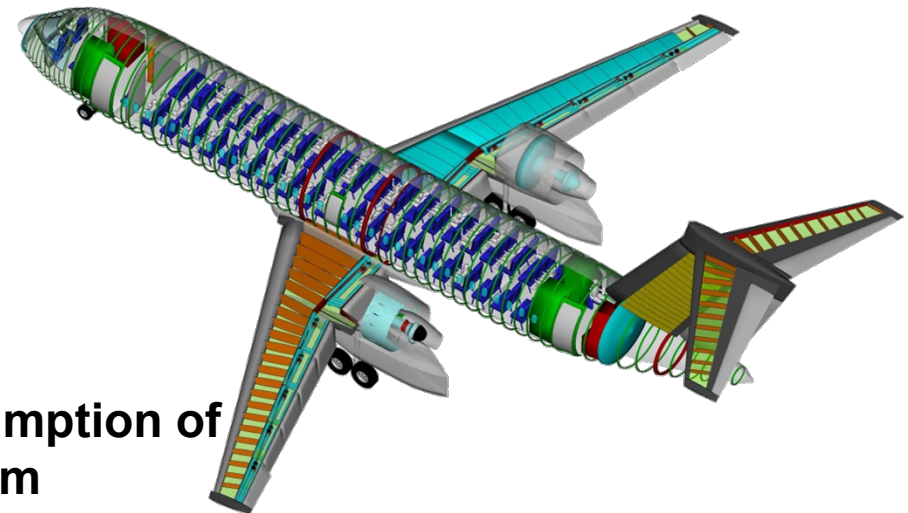
- Range: 2000km
- Capacity: 100 Pax
- STOL capability (800m)
- Reduced level of the ground noise

→Part A: Aero-acoustics

→Part B: **Efficient High-Lift**

→**Reduction of power consumption of Coanda-flap high-lift system**

→Part C: Flightdynamics



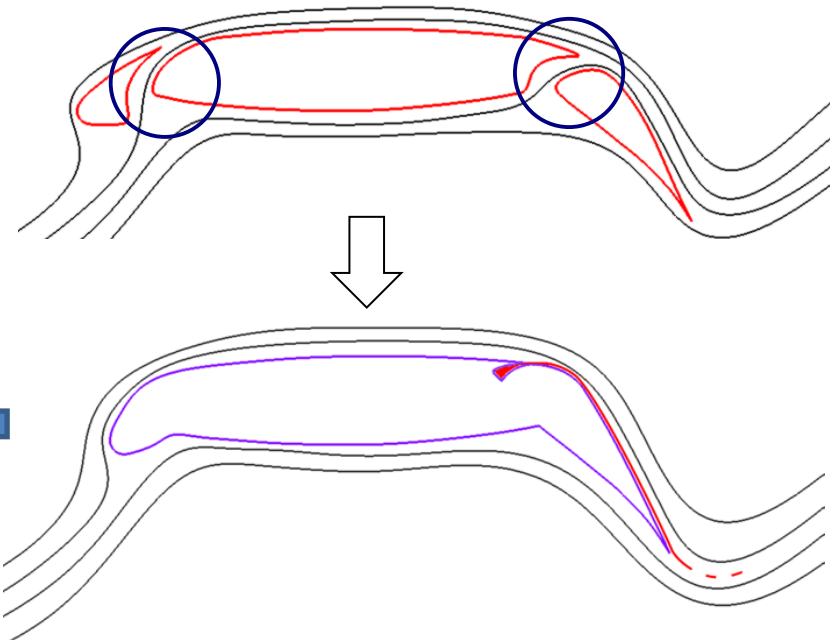
Motivation & Challenges for morphing leading edge

Large scale morphing

- Morphing leading edge for an active blown High-Lift system of a regional airliner
 - Gaps: noise and drag → Gapless active high lift system
 - Coanda effect is used for significantly increasing lift generation

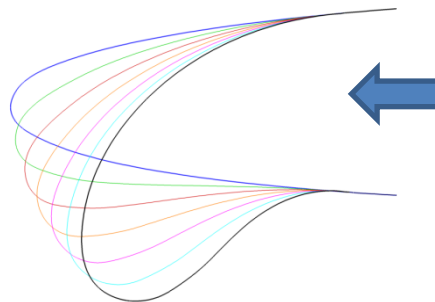


noise sources



Cruise position

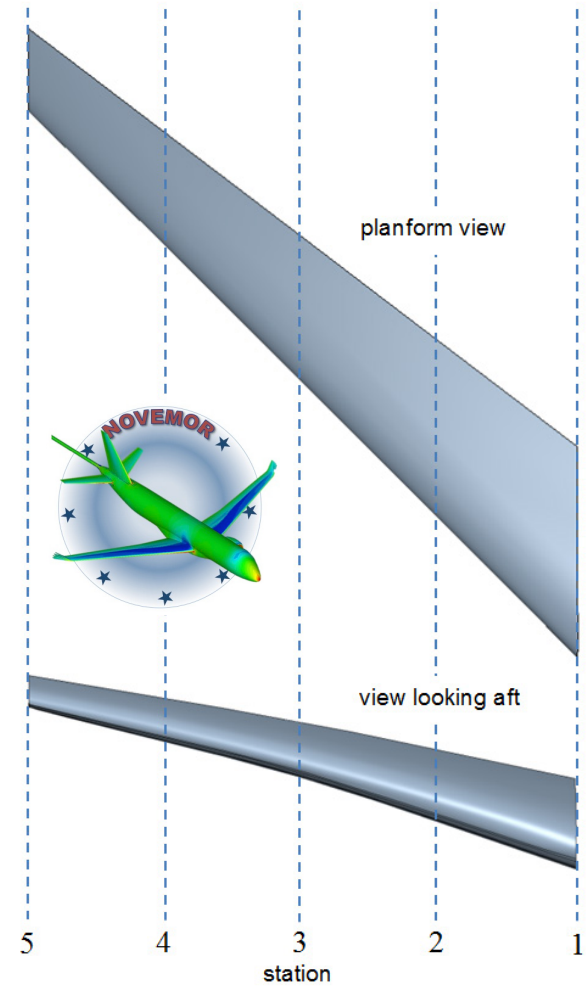
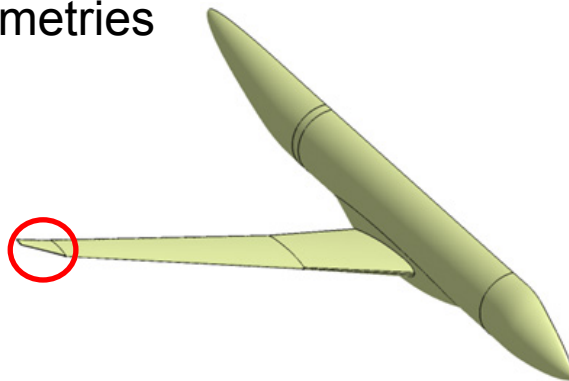
High-Lift position



Motivation & Challenges for morphing leading edge

3D morphing

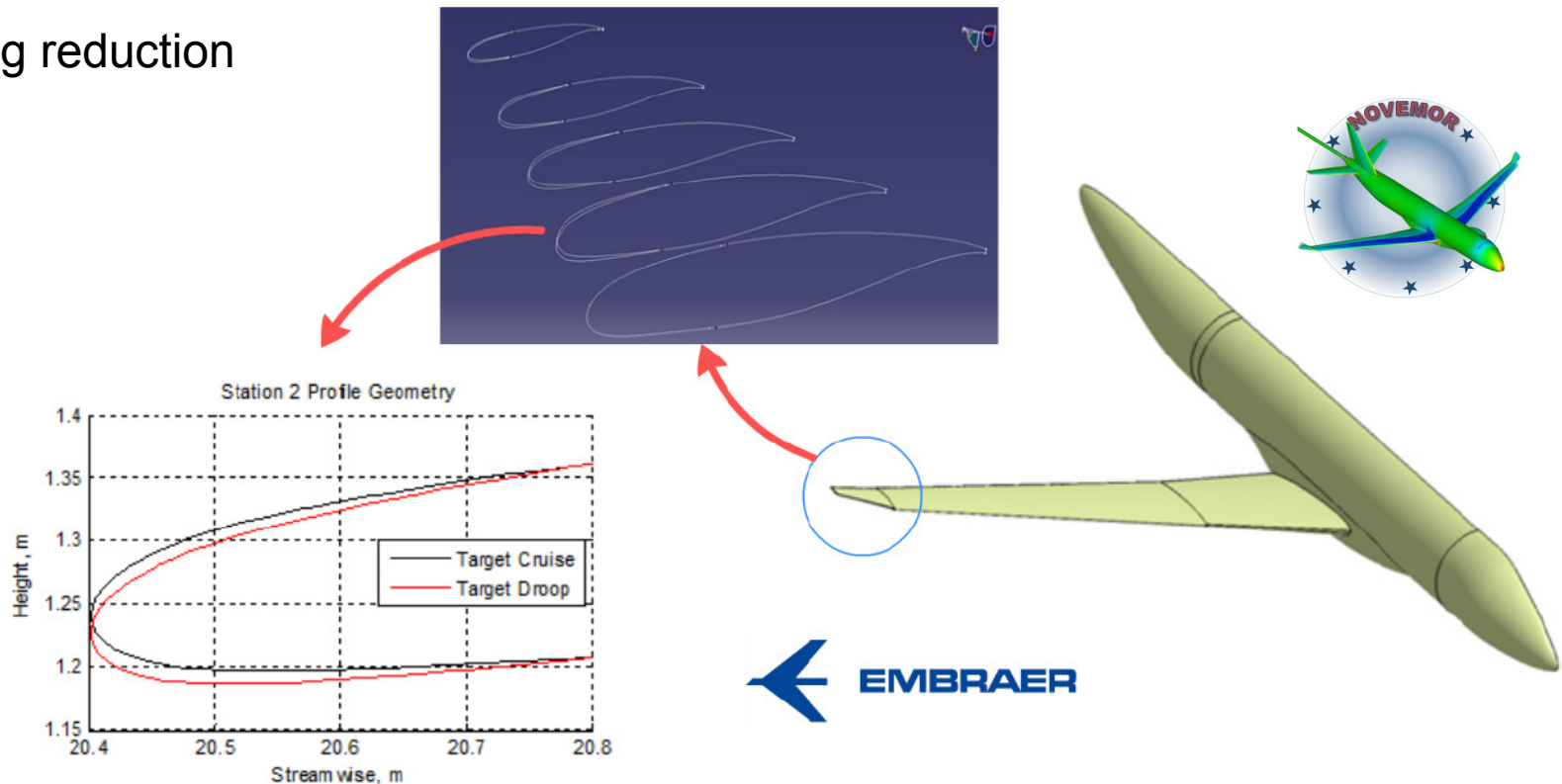
- Droop-nose morphing of a regional jet-liner wing-tip
 - Highly 3D
 - 35° sweep
 - Taper: chord and thickness
 - Dihedral
 - Double curvature
 - Streamwise morphing target shapes
 - Developing optimization tools to account for these geometries



Motivation & Challenges for morphing leading edge

3D morphing

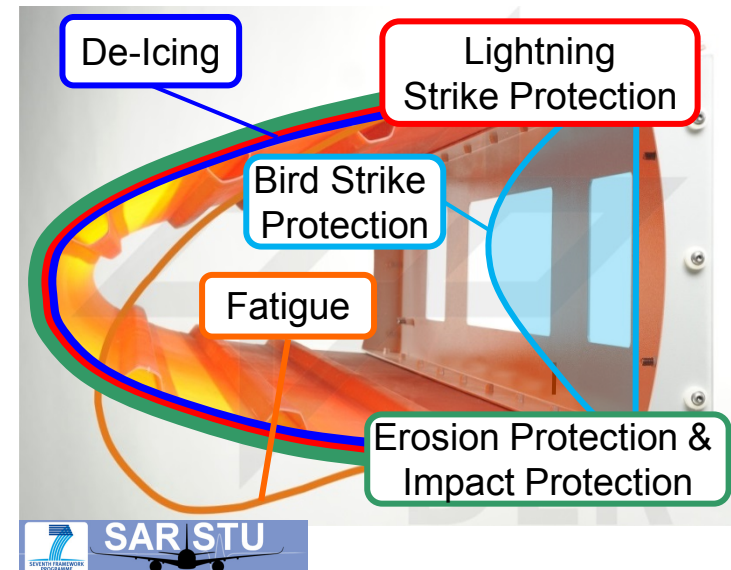
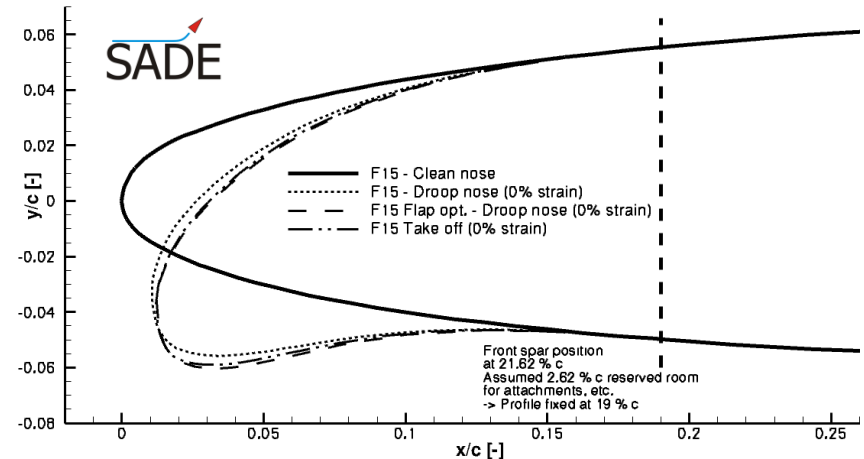
- Small morphing deflection: 2°
 - Aeroelastic benefits, e.g. prevention of aileron efficiency loss with increasing dynamic pressure
- Drag reduction



Motivation & Challenges for morphing leading edge

„The real world“

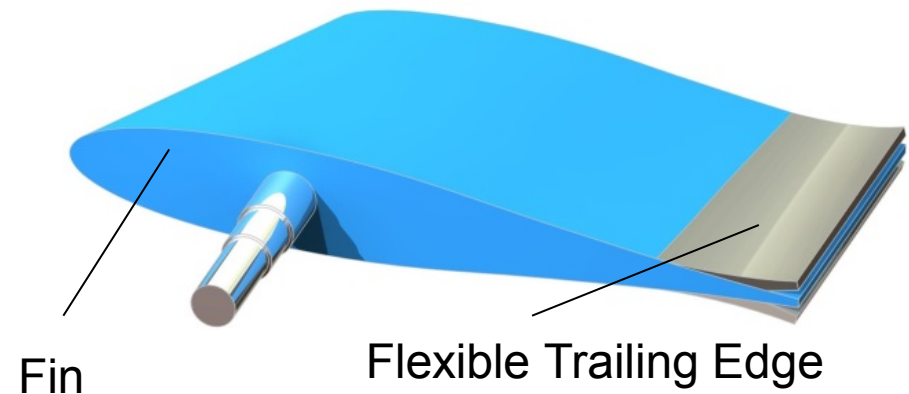
- Challenges for morphing devices
 - Large scale deformation
 - Integration of additional required functionalities
 - Concepts for integration and repair/maintenance
- Large Scale
 - Aeodynamic optimization of leading edge profile with max curvature difference $\pm 20\text{m}^{-1}$



Motivation & Challenges for morphing leading edge

„The real world“

- Challenges for morphing devices
 - Robustness at large scale deformation in combination with environmental conditions in operation:
 - Temperature (-50°C – $+90^{\circ}\text{C}$)
 - Sand/Rain Erosion
 - Corrosion (skydrol, marine water, ...)
- Example: Development of a morphing fin trailing edge with SKF, Blohm + Voss and partners for real life operational conditions



Overview

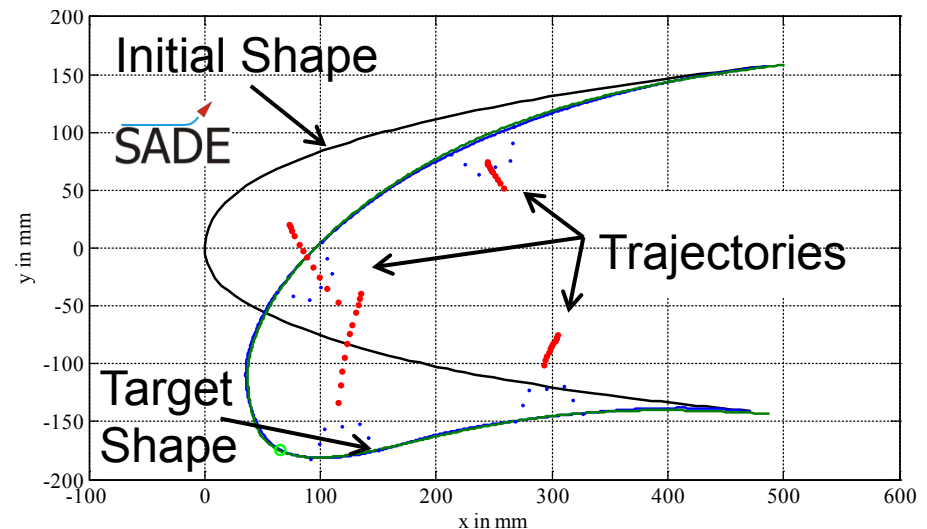
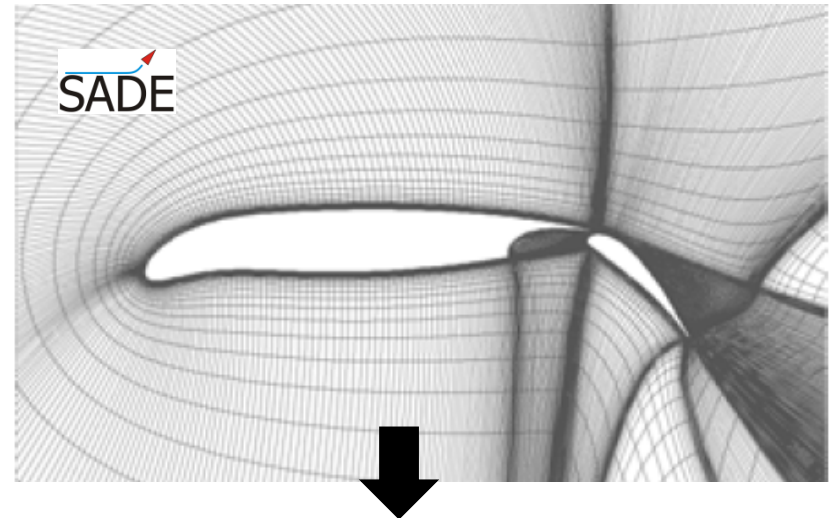
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Approaches for kinematics and compliant mechanisms

Kinematics design

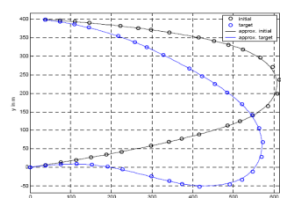
- Given **Target Shape**
 - Aerodynamic or Hydrodynamic optimization
- Structural Design
 - **Interface Points**
(Structure \leftrightarrow Mechanism)
- Design of Kinematics with **Trajectories**
 - Guidance Mechanism for the morphing structure during movement
 - Load transfer of aerodynamic/hydrodynamic loads



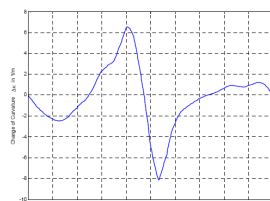
Approaches for kinematics and compliant mechanisms

Kinematics design

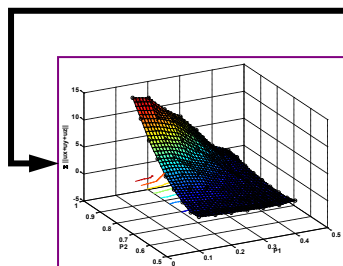
- Pre-Design of Skin and Kinematics (2D)



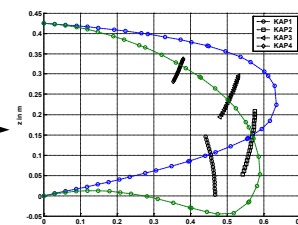
Aerod. Target Shape



Initial Skin Design

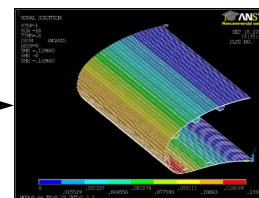


2D parametric FE,
Optimal Support Pos.

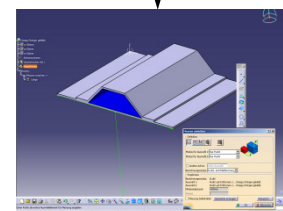
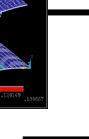


Kinematical Path, Strains,
Deformations, Stresses

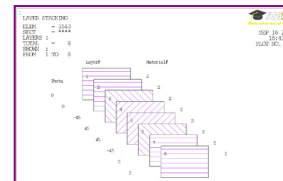
- Detailed Design (3D)



3D FE model



Optimization of the
Design of Omega-
Stringers wrt. stability
and strength
requirements



Optimization of layer
stacking sequence/
laminate layup wrt.
target shape, stability
and strength
requirements

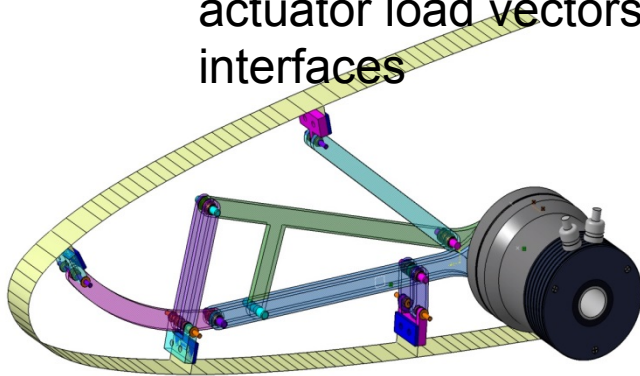


Feedback data
for other
disciplines

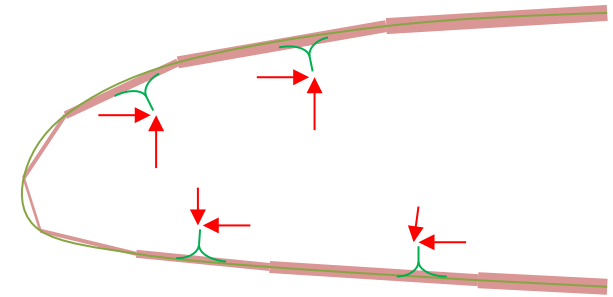
Approaches for kinematics and compliant mechanisms

Kinematics design

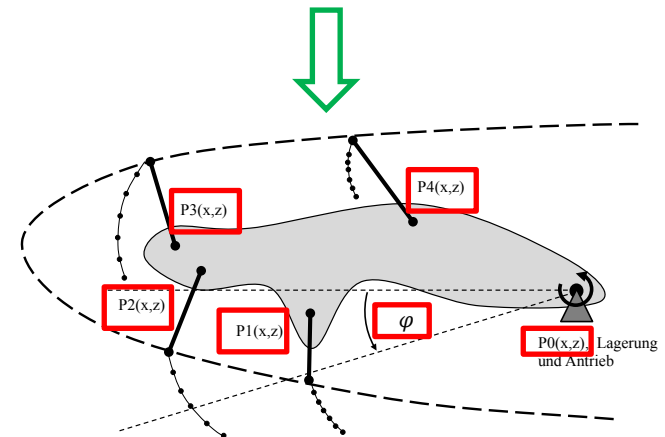
- **Design parameters** of the skin optimization:
 - Stiffness of skin segments along the skin perimeter
 - Thickness or layup variation, ...
 - Positions of the interfaces to the compliant kinematic system
 - Modulus and the direction of the actuator load vectors on these interfaces



CAD-construction of the morphing leading edge



Optimization of the skin and skin-to-kinematic interfaces



Optimization of the inward kinematic



Approaches for kinematics and compliant mechanisms

Skin & **Kinematics design (large scale morphing)**



Full-Scale morphing droop nose demonstrator

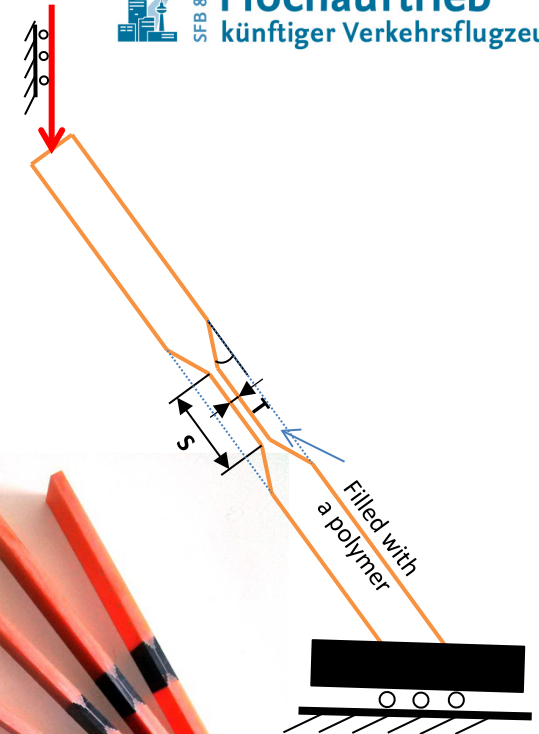
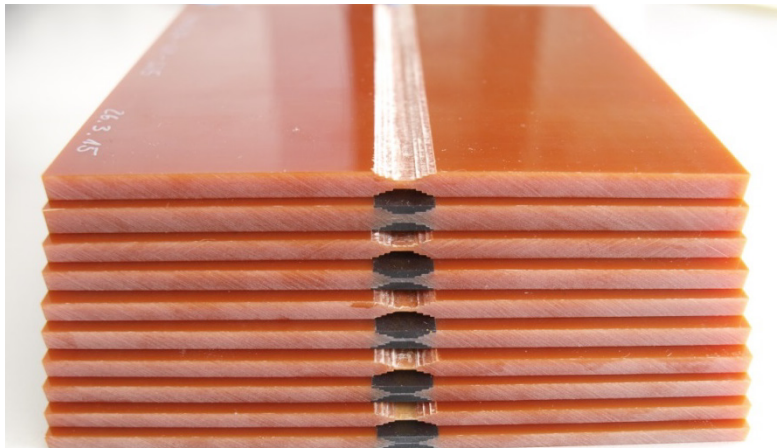


Approaches for kinematics and compliant mechanisms

Flexural Joints for Compliant Mechanisms



- Substitution of the state of the art kinematics by flexural joints and compliant mechanisms
- Numeric and experimental parametric studies on GFRP-Polymer joints under multiaxial loading



Approaches for kinematics and compliant mechanisms

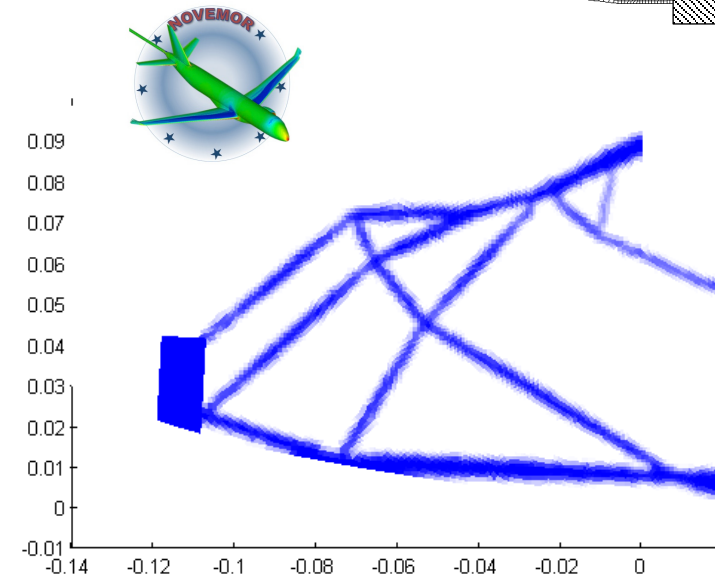
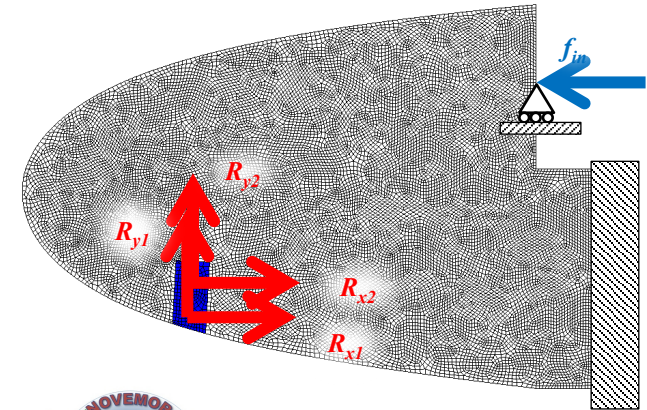
Compliant mechanisms design

Advantages of Compliant Mechanisms

- lightweight structures
- reduced assembly complexity
- no backlash

Topology Optimization

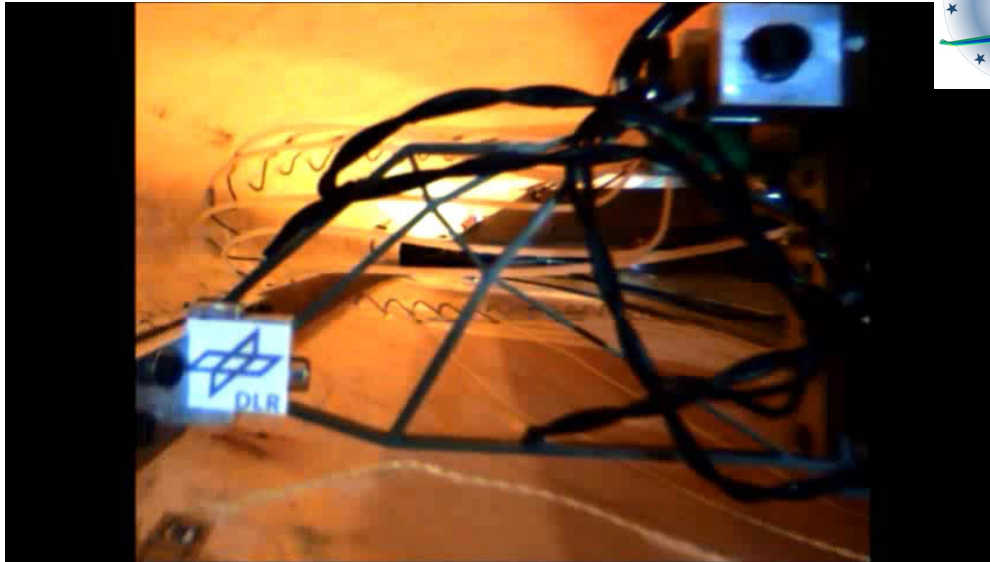
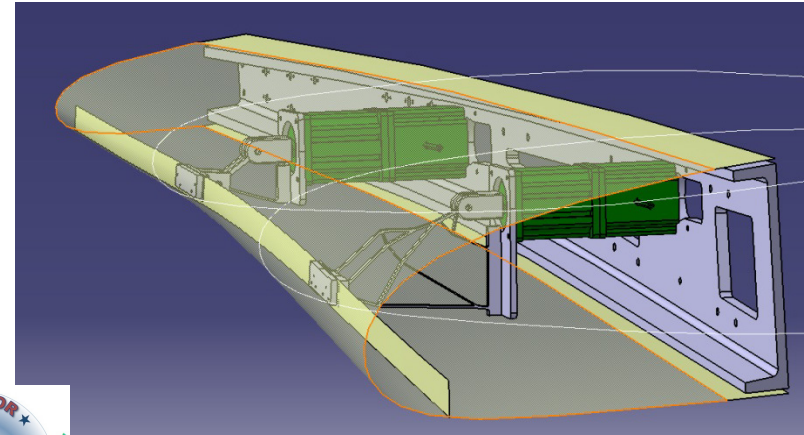
- find best structural layout starting from a “blank canvas”
- continuum gradient based via SIMP, sensitivity analysis and MMA
- 2D plane stress
- linear FEA routine (small target deflections)
- Shape control formulation: precision displacement
- Stiffness functions: load capability



Approaches for kinematics and compliant mechanisms

Compliant mechanisms design

- Topology post-processed
- Superelastic nickel titanium (>2% strain)
- Manufactured by wire electrical discharge machining (EDM, 5 mm plate form)



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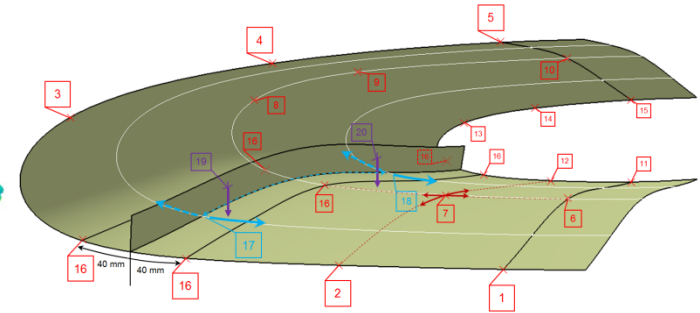


Approaches for skin design

GFRP 3D



- tailored stiffness:
 - optimized skin thickness distribution
- thickness achieved via appropriate ply stacking
- GFRP Hexcel HexPly® 913 prepreg plies
- skin – compliant substructure interface: stringer
 - i.e. load introduction point
- 2D concept of SADE program →
 - Re-developed in a 3D environment in NOVEMOR
- Simplex algorithm
- automated and iterative
- objective function: LSE clean and droop configurations
 - multiple FEA solutions via Ansys:
 - combined shape change and stiffness functionality



DVs 1 – 16:

- skin thickness at 21 points
- [1 – 4] mm
- bilinear interpolation

DVs 17 – 18:

- stringer position at stations 2 and 4
- [35 – 55] % station perimeter length
- spline interp. and extrap.

DVs 19 – 20:

- force magnitude at CM stations
- [50 - 650] N



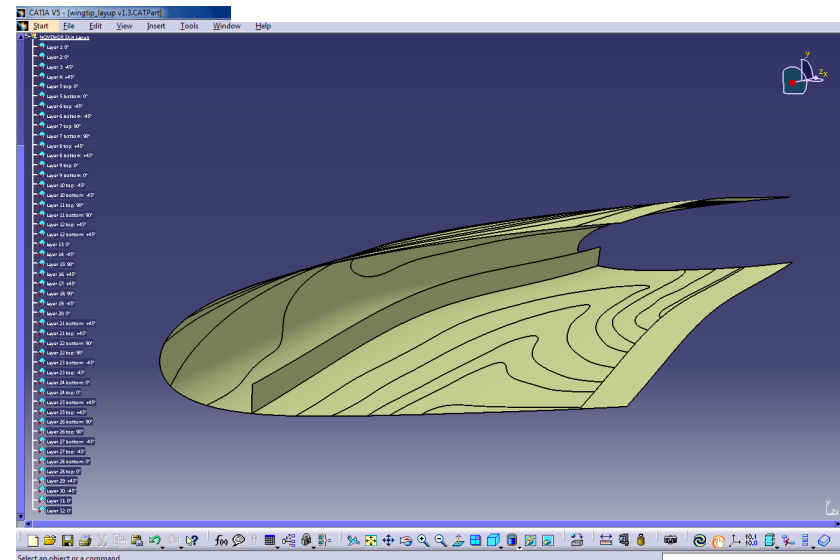
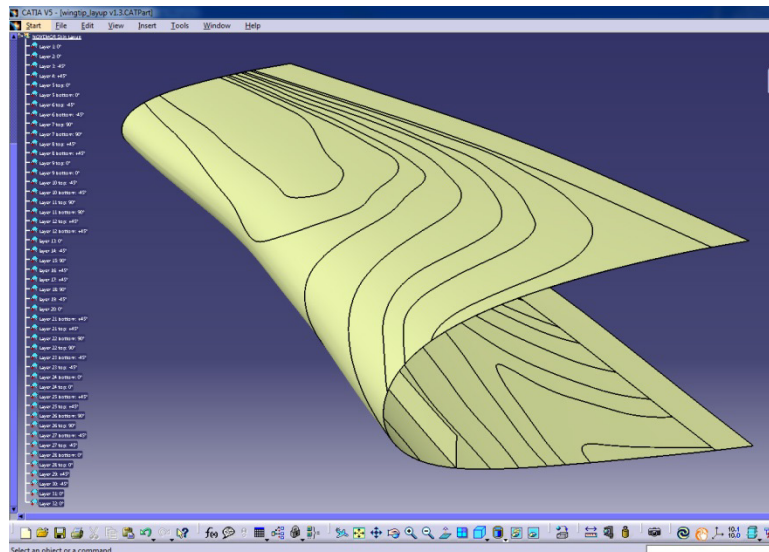
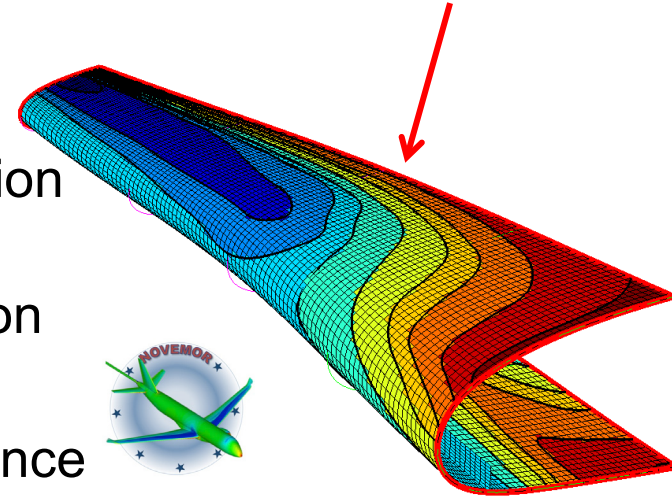
Approaches for skin design

GFRP 3D

3DSkinOpt post-processing

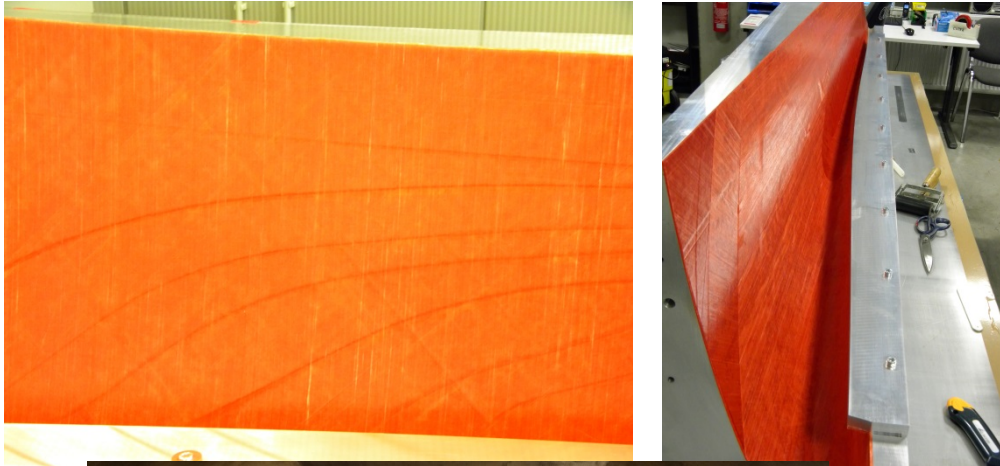
- algorithm established for ordered edge detection
- LSE 3D spline-fit based on coordinate parameterization for smooth contour generation
- export files to CAD
- 32 plies (HexPly® 913) as per stacking sequence

smooth contours



Approaches for skin design

GFRP 3D



Wind tunnel tests, Feb. 2015

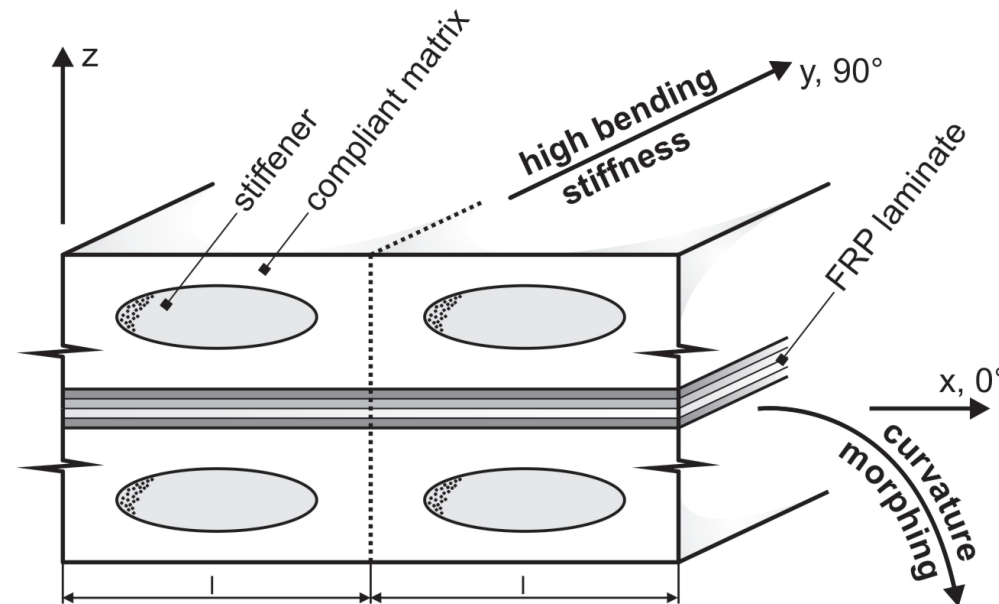
- Univ. of Bristol, 7' x 5'
Low speed
- Assessment of
structure (skin and
compliant
mechanisms) under
aerodynamic loads



Approaches for skin design

GFRP-EPDM

- Hybrid skin design for high anisotropic skins
- High-Strain capability through combination of GFRP/EPDM-rubber (synthetic rubber)
- Combination of GFRP laminate with C/GFRP stiffeners in a rubber matrix
- Flexibility in chord direction – stiffness in span direction



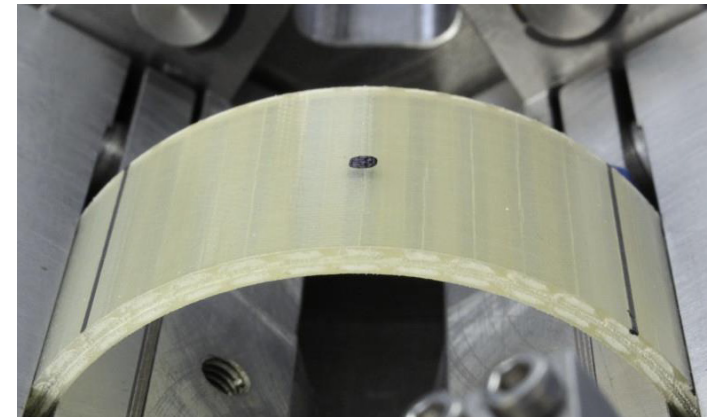
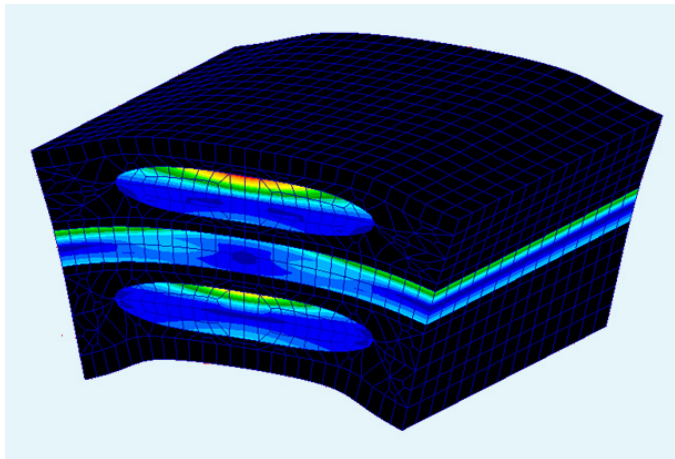
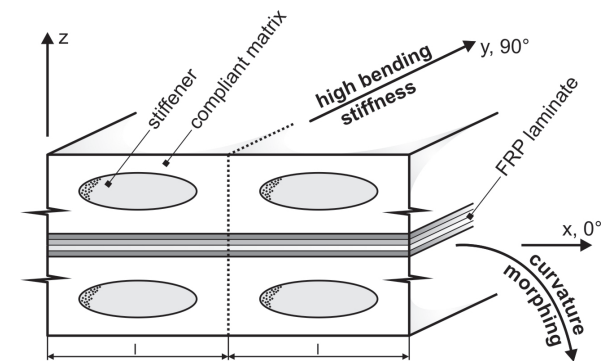
Source: Andre Schmitz, IFL, TU-Braunschweig



Approaches for skin design

GFRP-EPDM

- A representative FE-element of a hybrid skin under bending load
 - Parametric boundary conditions
 - Reduced order modeling for large scale applications
- Experimental validation of the FE models
- Strength and fatigue investigations



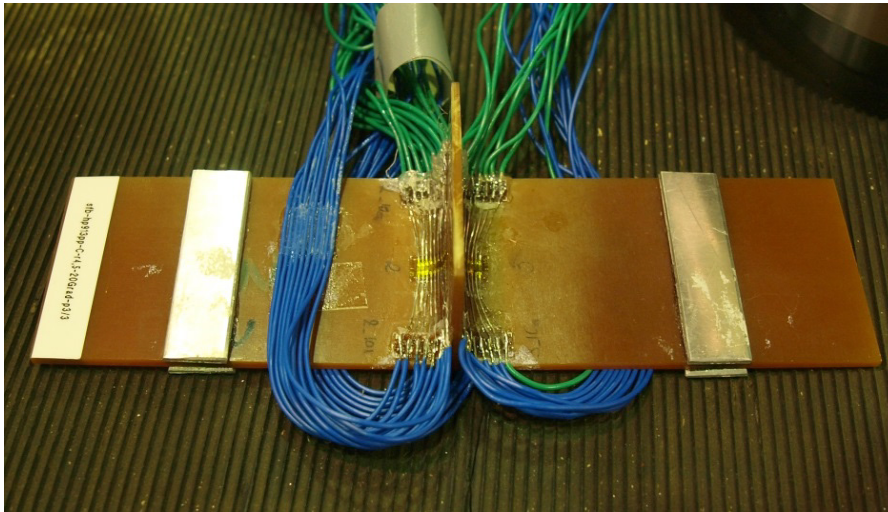
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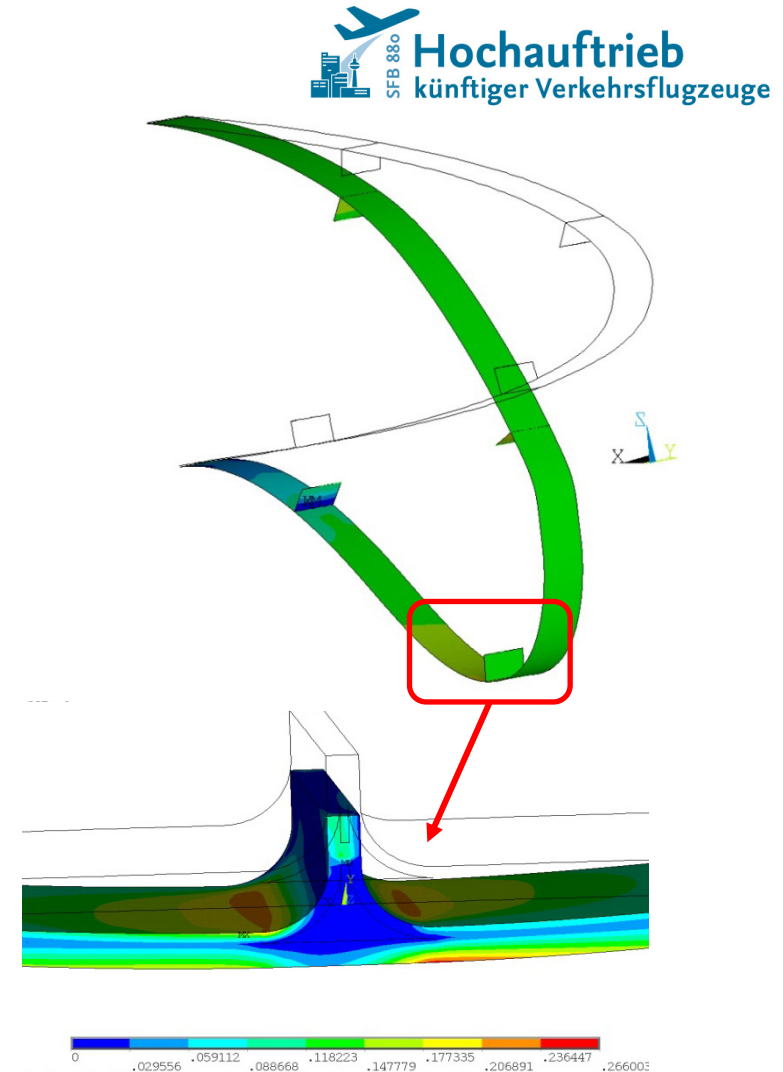
Approaches for skin design

GFRP-EPDM

- Experimental and numerical investigations on the skin-kinematic interfaces
- Integration of dense meshed solid models in the optimization routines



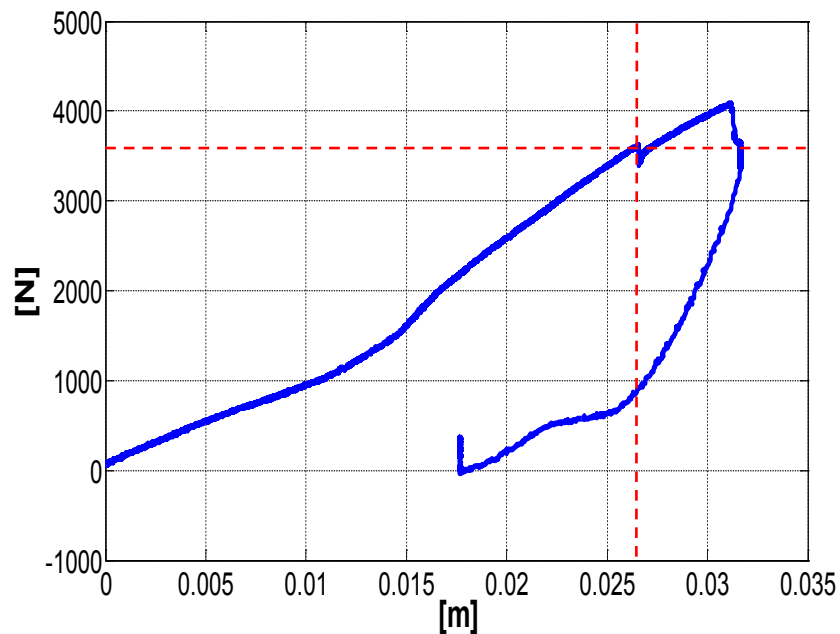
A specimen with 30 micro strain gages in curved surfaces for the model validation



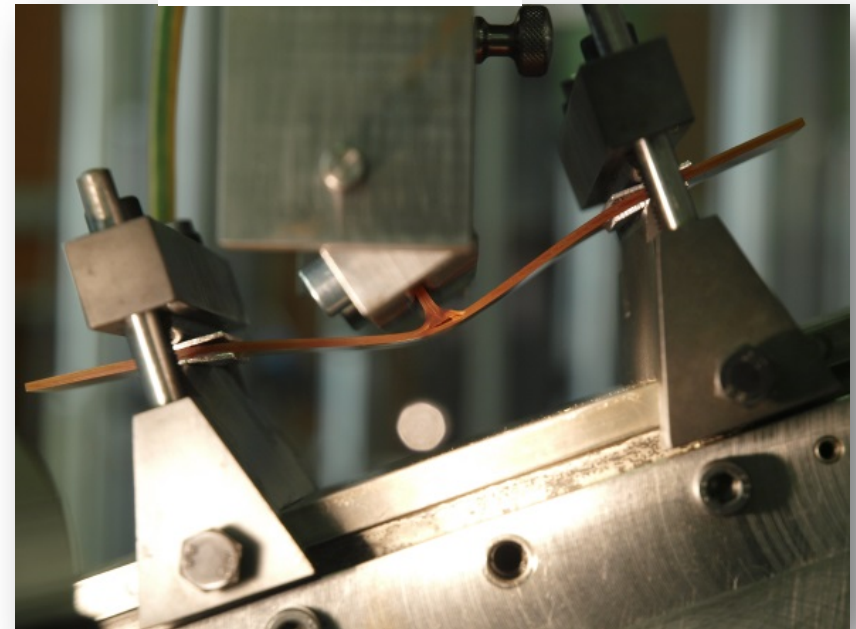
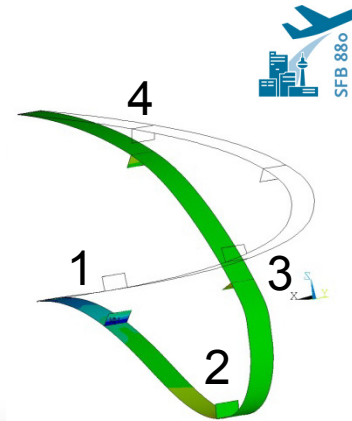
Approaches for skin design

GFRP-EPDM

- Strength of the interface under realistic loads



Force – Displacement Curve of loading under 20° force application



Test of a double-L interface with a force under 20° load application

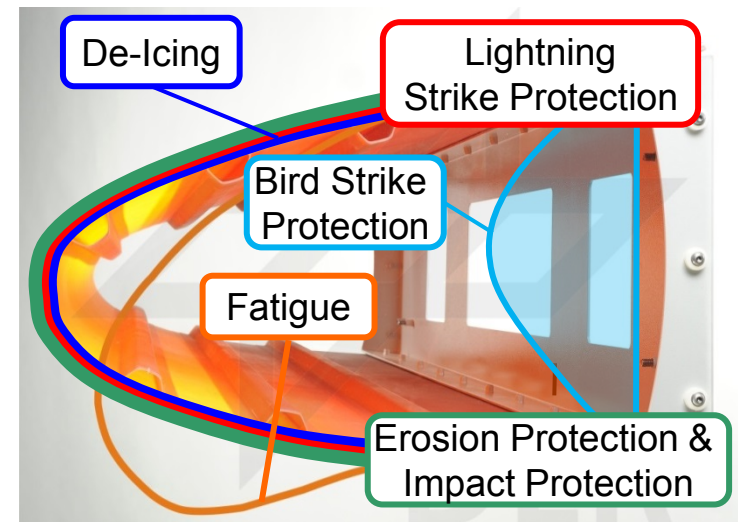


Approaches for skin design

GFRP with integrated layers

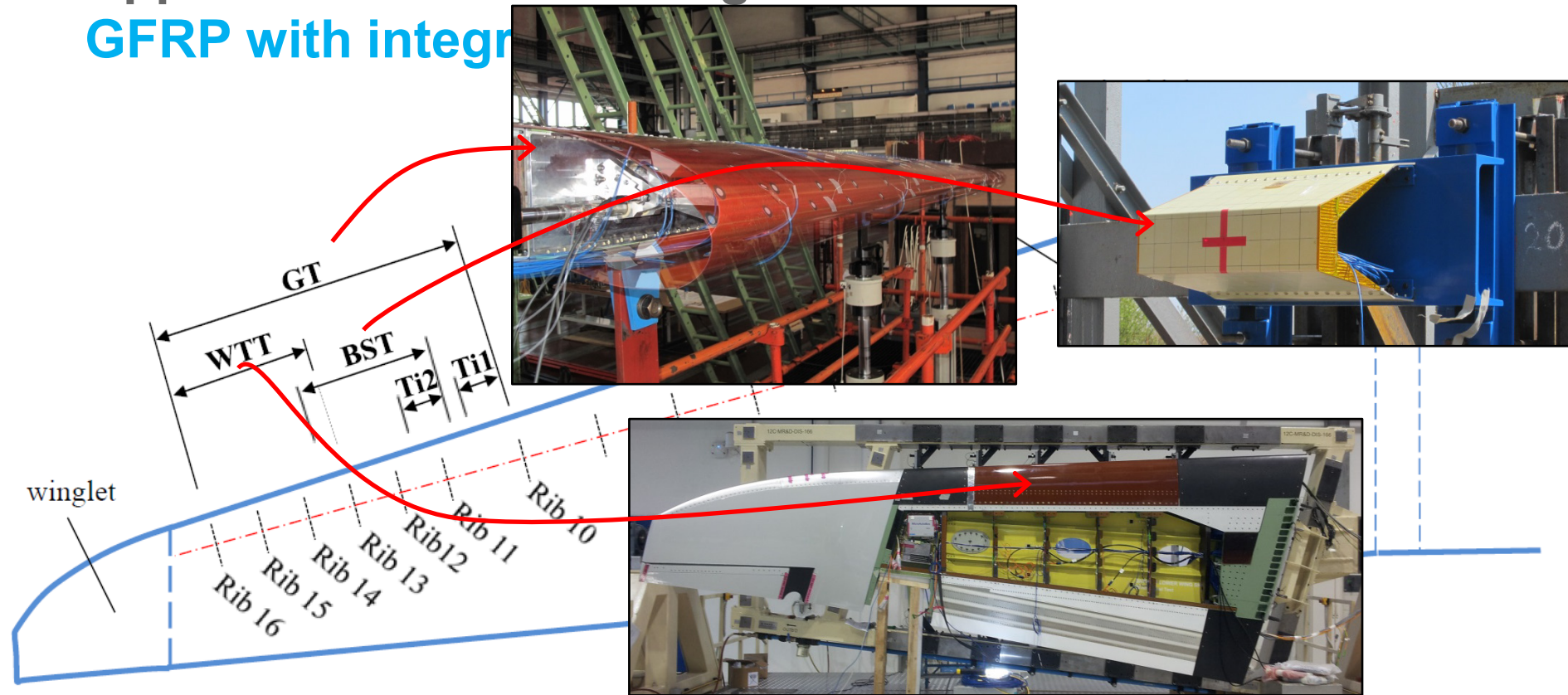


- Integration of additional functionalities into a 'baseline' GFRP skin concept
 - Ice Protection System (IPS)
 - Lightning Strike Protection (LSP)
 - Erosion & Impact Protection
 - Bird Strike Protection
 - Improved Fatigue Behaviour



Approaches for skin design

GFRP with integr



Acr.	Rib Station	Length	Test/Demonstrator	Topic
GT	Rib 10 – Rib 16	3656mm	Large scale test: wing bending, cyclic, heater-mat	Shape, Strain, Strength
WTT	Rib 13 – Rib 16	1760mm	Test under aerodynamic loads	Shape, Strain
BST	Rib 11 – Rib 12	1600mm	Bird Strike Tests, 3 configs: 2x splitter, 1 hybrid	Bird Strike Performance
Ti1	Rib 10	300mm	Demonstrator with Ti-foil (full-chord) & heater-mat	Shape
Ti2	Rib 11	300mm	Small scale test with Ti-Foil (Patch)	Shape, Strain, Strength

Approaches for skin design

GFRP with integrated layers

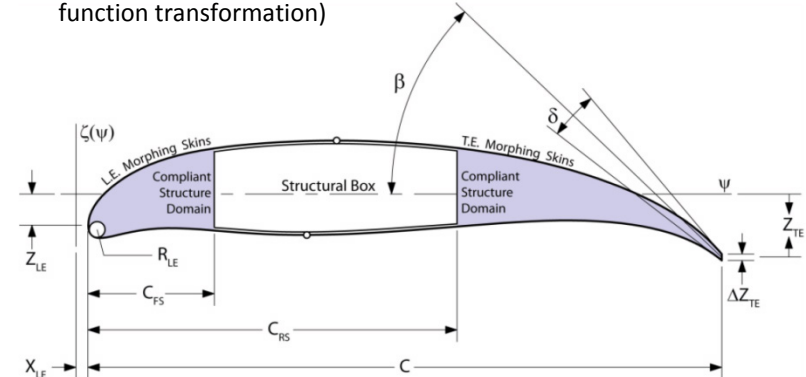
→ Basic Design Specifications

→ (Pre-) Design based on target shapes

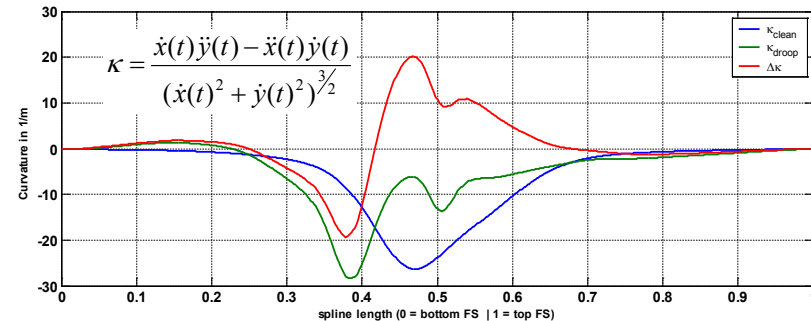
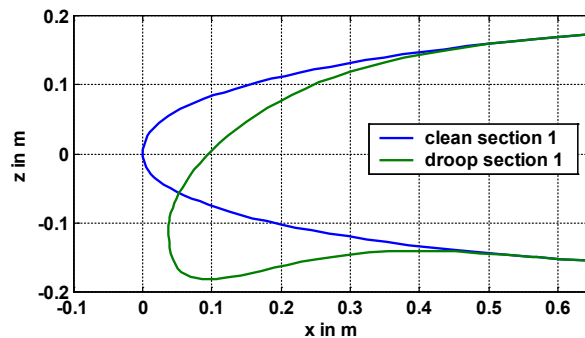
- Parametric Description of aerodynamic profile
- Aerodynamic Optimization (High-Lift, Cruise(VC))
- Assessment of Structural (Geometric) Boundary Conditions



Parameterization of the profile for CST method (class/shape function transformation)



Source: S. Ricci, A. Gaspari: "Combining Shape and Structural Optimization for the Design of Morphing Airfoils", 2nd International Conference on Engineering Optimization, September 6-9, 2010, Lisbon, Portugal



Approaches for skin design

GFRP with integrated layers

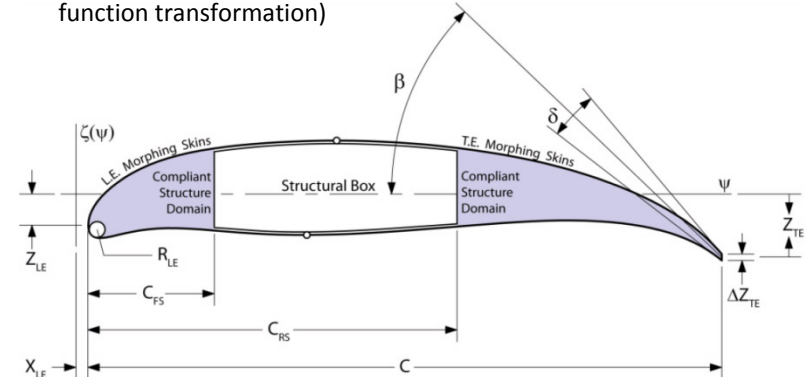
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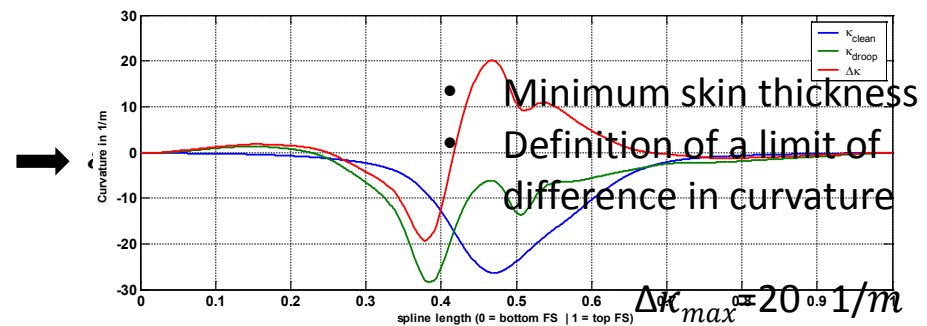
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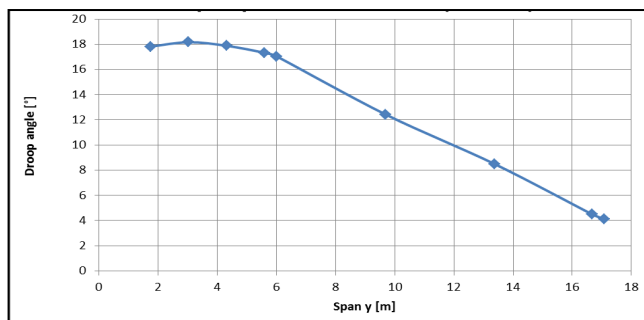
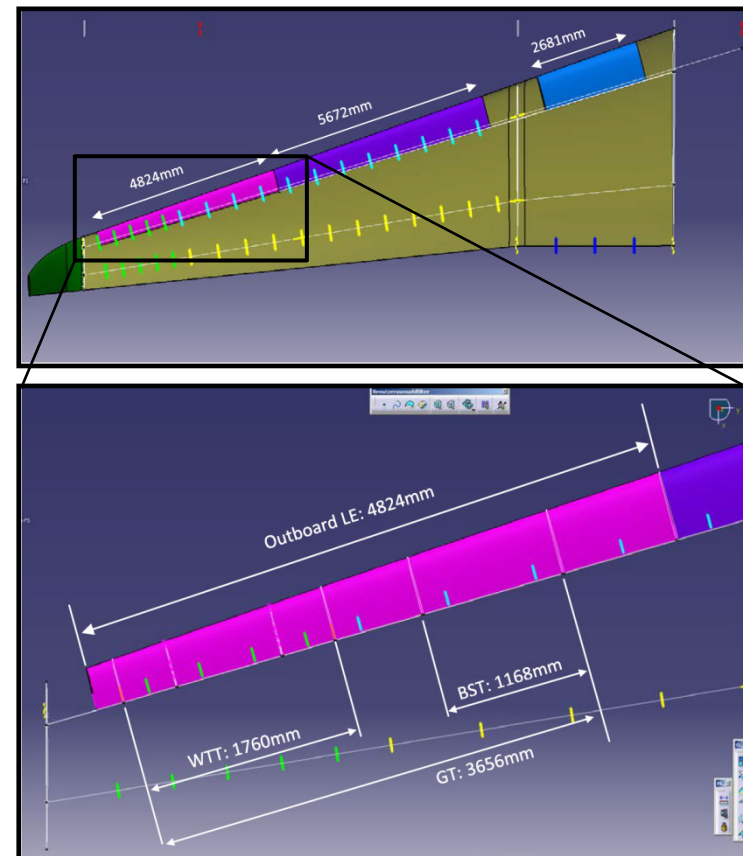


Approaches for skin design

GFRP with integrated layers

“Integrated Structure and System Concept Definition”

- **Overall wing leading edge sections**
 - Three leading edge sections
 - Two Outboard Sections
 - One Inboard Section
 - Kinematic Stations are consistent with given rib positions
- Integration of bird strike protection and kinematics
- Integration of additional functional layers



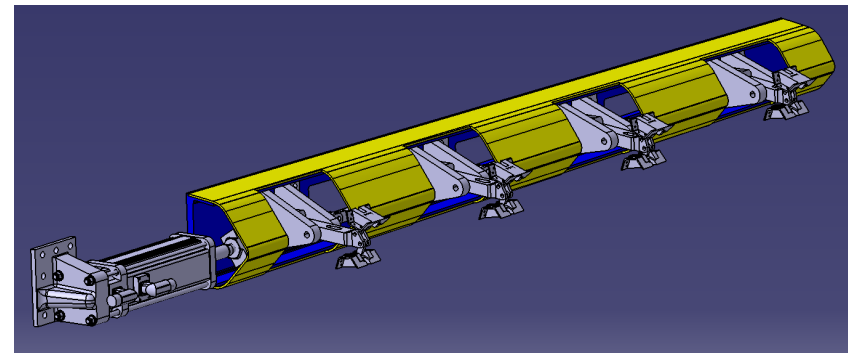
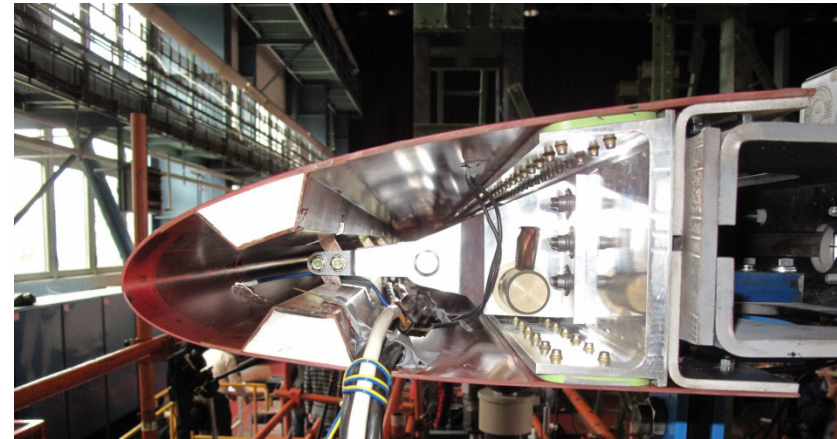


Approaches for skin design

GFRP with integrated layers

“Integrated Structure and System Concept Definition”

- Overall wing leading edge sections
 - Three leading edge sections
 - Two Outboard Sections
 - One Inboard Section
 - Kinematic Stations are consistent with given rib positions
- **Integration of bird strike protection and kinematics**
→ Design Space is limited!
- Integration concept of additional functional layers



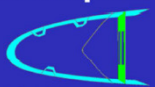
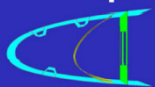
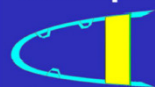
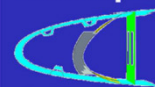
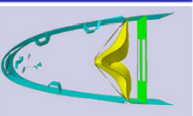
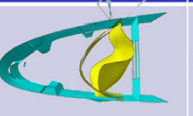
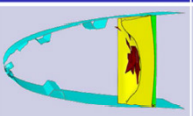
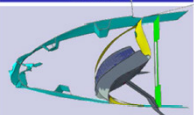
Approaches for skin design

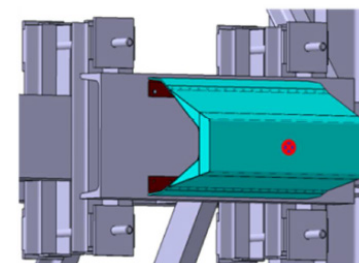
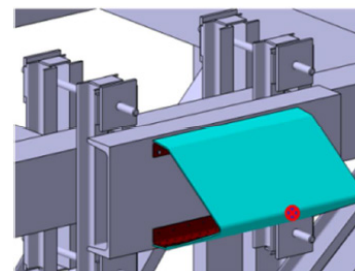
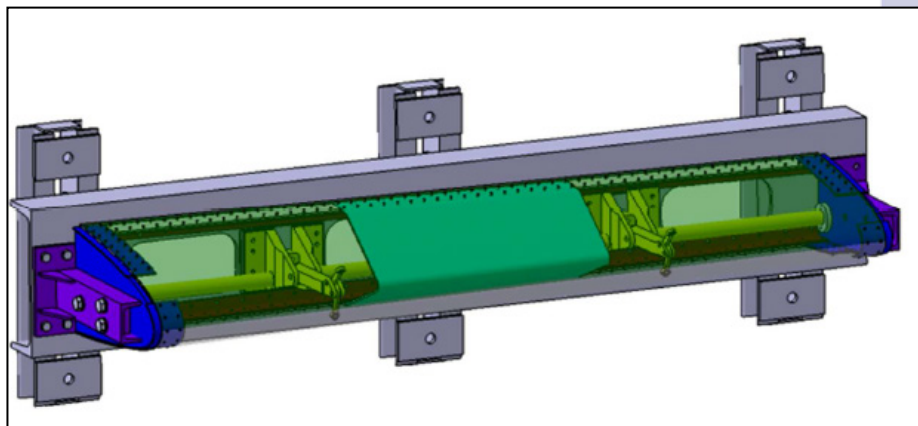
GFRP with integrated layers

→ Integration of bird strike protection and kinematics

- Shot on morphing leading edge with integrated bird splitter and separate hybrid splitter concept



	Concept 1	Concept 2	Concept 3	Concept 4
	 Bird Splitter with a circular edge in the nose	 Inner Dnose skin, designed to maximize the space allocation	 Honeycomb panel attached to the subspar.	 Combination of the inner Dnose and the honeycomb panel concept.
Final BSPS Damage				
BSPS masses	2.18 Kg	2.63Kg	3.19Kg	3.43 Kg
Spar protection	Not impacted	impacted	plastified	Not impacted
System Space allocation	Probably not sufficient	Better than concept 1	No space allocation	Better than concept 1
Scenario Description	<ul style="list-style-type: none"> • Nose skin perforated. • Acting as a bird splitter. • BSPS is highly deformed and locally torn. • bird is split and is flowing along the slopes of the BSPS, it leads to the bottom and top failure of the nose skin but the spar is protected. 	<ul style="list-style-type: none"> • Nose skin perforated. • Bird is dragging away the BSPS toward the subspar, the spar is finally impacted. • The BSPS is highly deformed and locally torn. • A part of the bird is flowing along the BSPS and perforate the nose skin. 	<ul style="list-style-type: none"> • Bird stopped • Spar plastified 	<ul style="list-style-type: none"> • Nose skin perforated • BSPS is highly deformed and plastified. • the majority of the bird kinetic energy is absorbed. • A part of the bird is flowing along the BSPS and perforate the nose skin but the spar is protected.



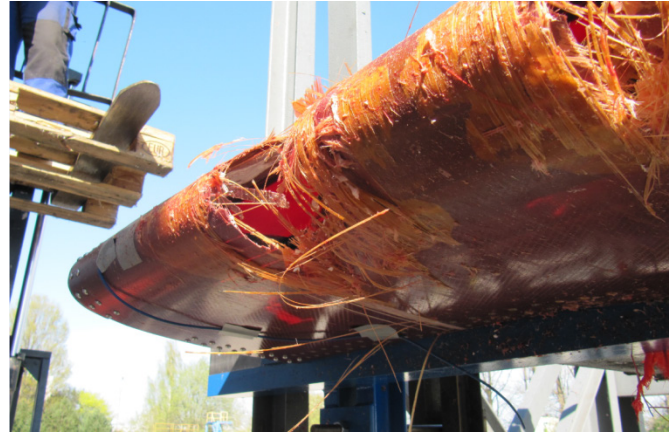
Approaches for skin design

GFRP with integrated layers



Approaches for skin design

GFRP with integrated layers



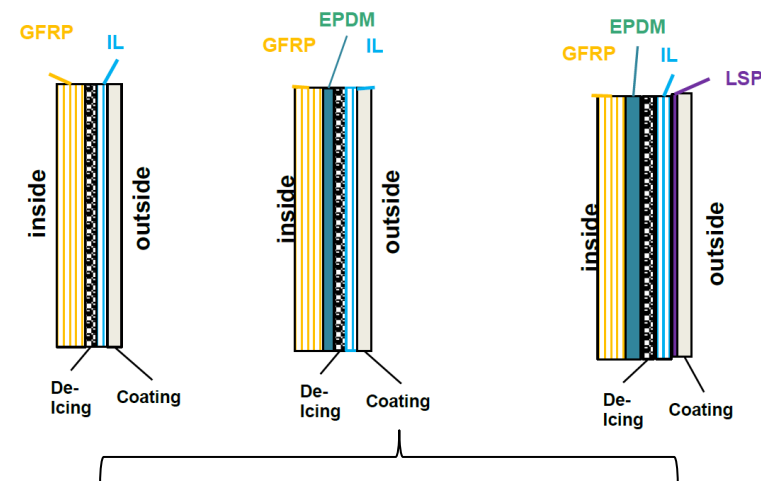
Approaches for skin design

GFRP with integrated layers



“Integration of additional functionalities”

- Overall wing leading edge sections
- Integration concept of BSPS and kinematics



• Integration concept of additional functional layers

- Surface Protection
- De-/Anti- Icing
- Impact Resistance
- Lightning Strike Protection

Comparison of rain and solid particle erosion durability of different materials

	Metall		Paint		Rubber		Hard coating	
Rain erosion (20 – 3000 impacts, 225 m/s, 2 mm drop size)								
Solid particle erosion (5 g silica sand 220 µm, 55 m/s, 2 g/min)	20° 	90° 	20° 	90° 	20° 	90° 	20° 	90°



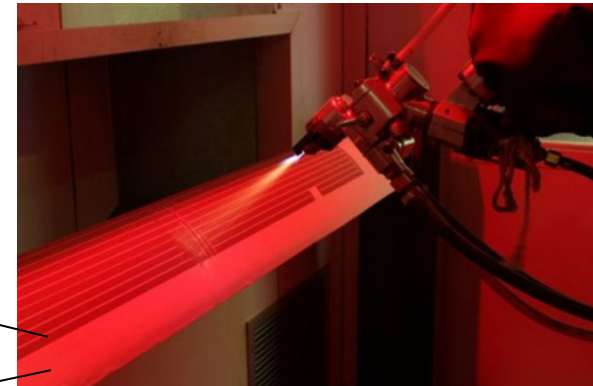
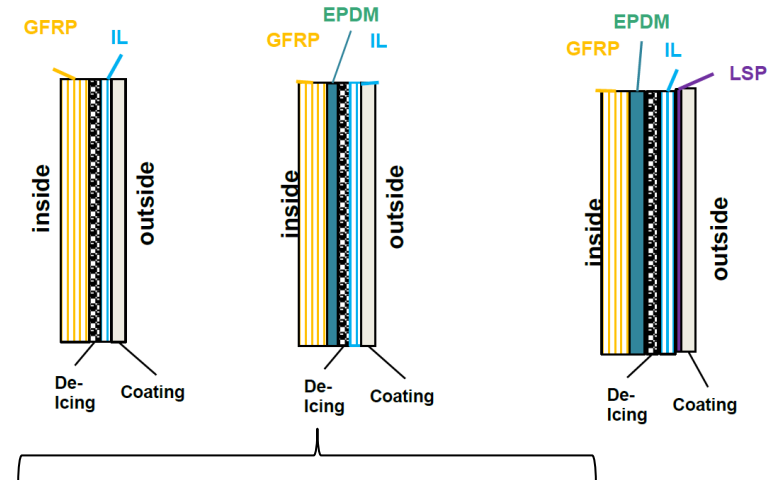
Approaches for skin design

GFRP with integrated layers



“Integration of additional functionalities”

- Overall wing leading edge sections
- Integration concept of BSPS and kinematics
- **Integration concept of additional functional layers**
 - Surface Protection
 - **De-/Anti- Icing**
 - Impact Resistance
 - Lightning Strike Protection



Conductive paths

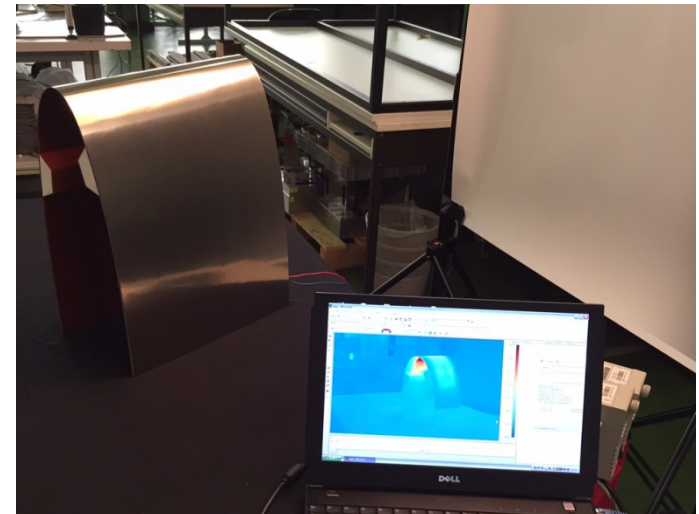
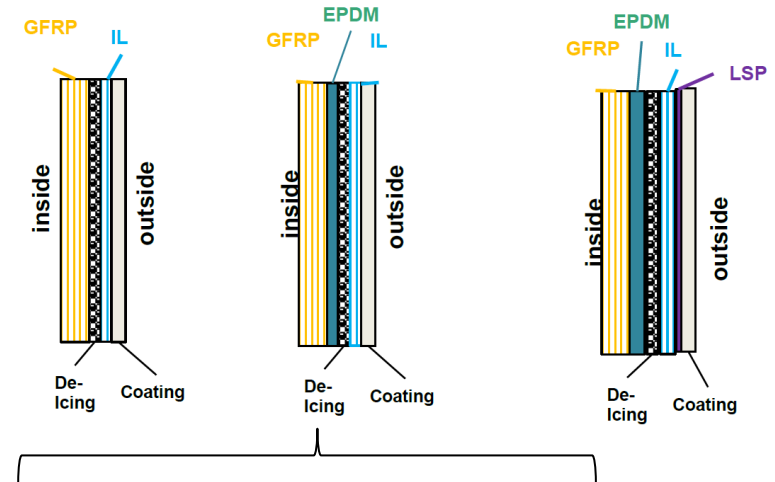
GFRP substrate

Source: GKN



Approaches for skin design

GFRP with integrated layers



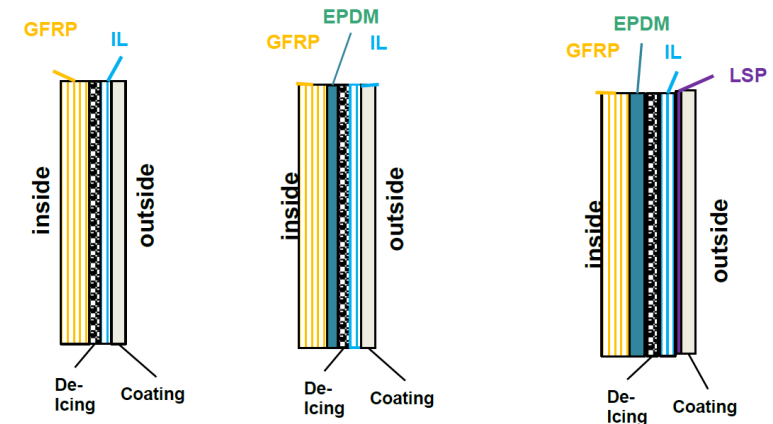
“Integration of additional functionalities”

- Overall wing leading edge sections
- Integration concept of BSPS and kinematics
- **Integration concept of additional functional layers**
 - Surface Protection
 - **De-/Anti- Icing**
 - Impact Resistance
 - Lightning Strike Protection

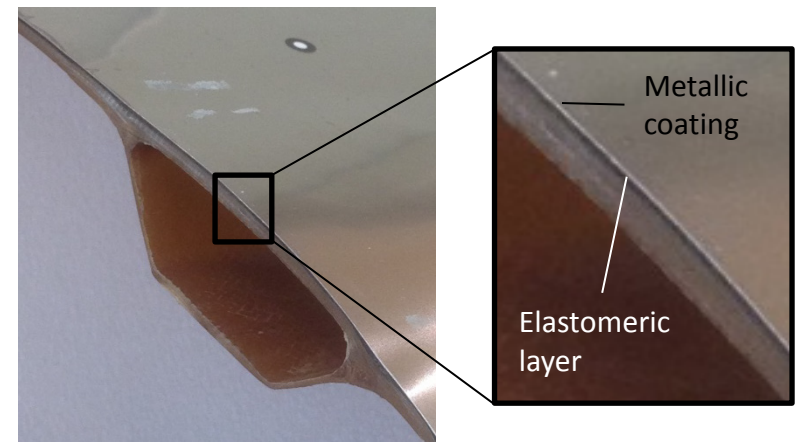


Approaches for skin design

GFRP with integrated layers



- Overall wing leading edge sections
- Integration concept of BSPS and kinematics
- **Integration concept of additional functional layers**
 - Surface Protection
 - De-/Anti- Icing
 - **Impact Resistance**
 - **Lightning Strike Protection**





Approaches for skin design

GFRP with integrated layers

- Limited Design Space at outboard: Integration brackets can be realized but lead to strain peaks (which limit the degree of morphing) and local stiffening in chord (which increases local changes in curvature when deployed, waviness)
- Metallic erosion protection shields make the tailoring to target shapes difficult due to their high stiffness and exhibit a poor fatigue behavior
- Max. Strain: Functional Layers to be integrated must be high strain capable and must be designed as thin as possible
- IPS: The dielectric properties of the basic material must be improved. It triggers additional thickness due to electr. isolation and for their part again higher heater-mat temperatures due to thermal isolation
- Lightning strike protection without application of metallic foils needs to be investigated



Approaches for skin design

Polyurethan with foam

- Structural Concept for a Morphing (FIN) Trailing Edge

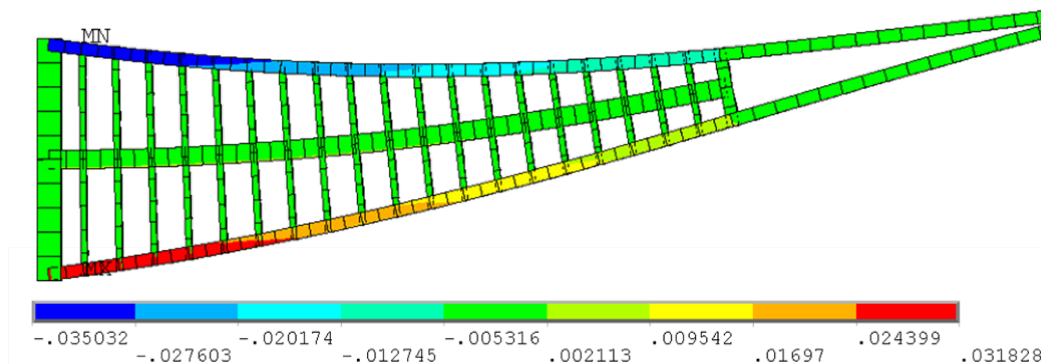


Fig.: Pre-Design Finite Element Analysis: Strain Distribution in Deployed Position

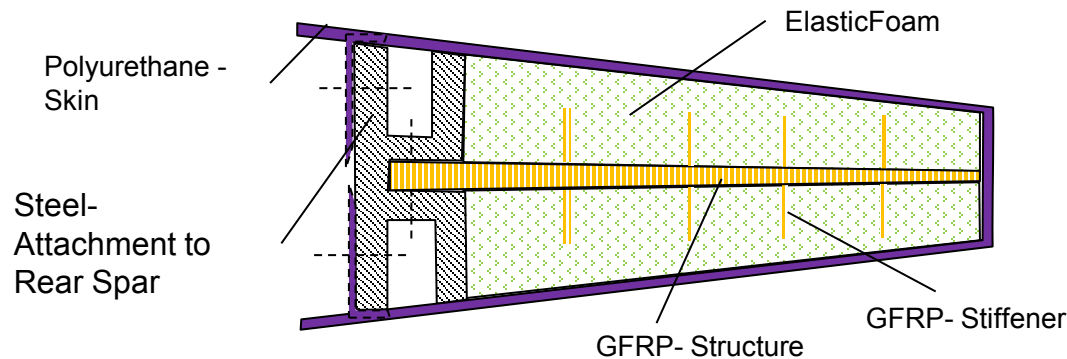
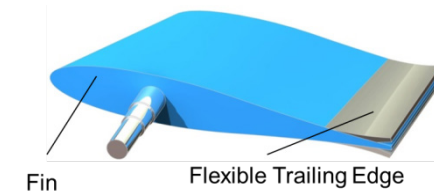


Fig.: Design Concept for Integrated Stiffeners and Material Combination



Approaches for skin design

Polyurethan with foam

- Development of a morphing trailing edge fin
 - Material combination of
 - GFRP
 - Polyethylene Foam
 - Polyurethane Skin
- Coupon and Component Tests
 - Static material tests under environmental conditions i.e. temperature and marine water in combination
 - large scale cyclic component test

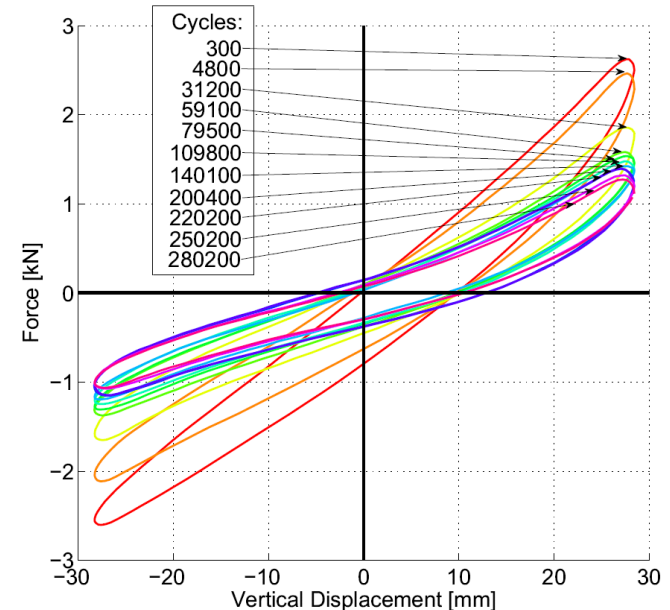
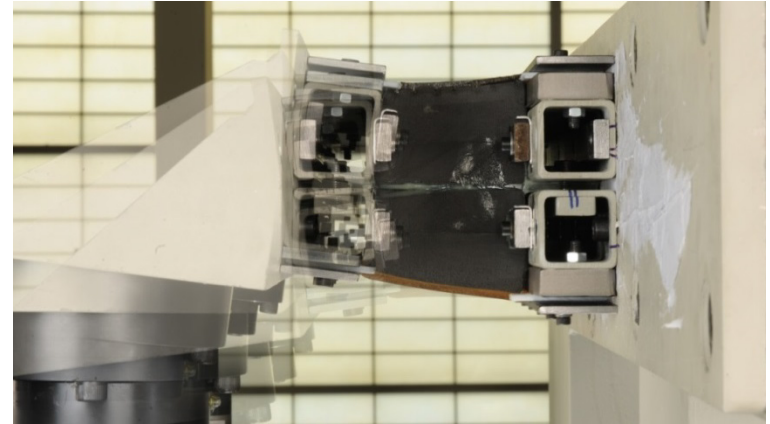
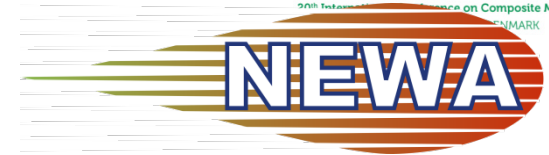


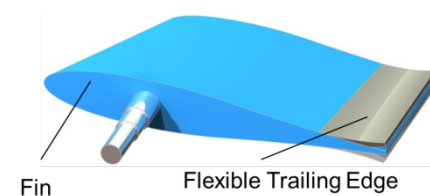
Fig.: Results of cyclic tests of the morphing trailing edge segment



Approaches for skin design

Polyurethan with foam

- Continuous increasing complexity and details in FEA Design combined with validation by experimental tests
 - Variant 0: 2-dimensional, GFRP
 - Variant 1: 2-dimensional, GFRP + PU-Foam
 - Variant 2: 2-dimensional, GFRP + different foams
 - Variant 3: 2-dimensional, GFRP + PE-Foam + PU-Skin
 - Variant 4: **3-dimensional**, GFRP + PE-Foam + PU-Skin



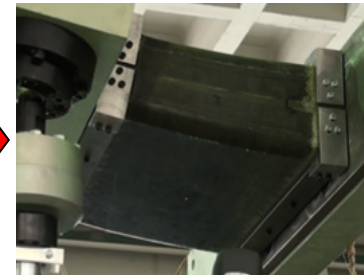
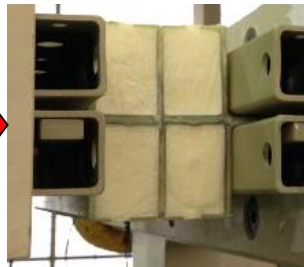
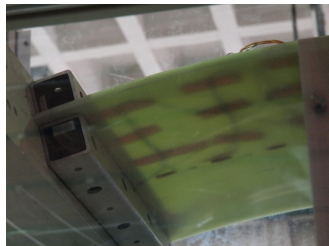
Variant 0

Variant 1

Variant 2

Variant 3

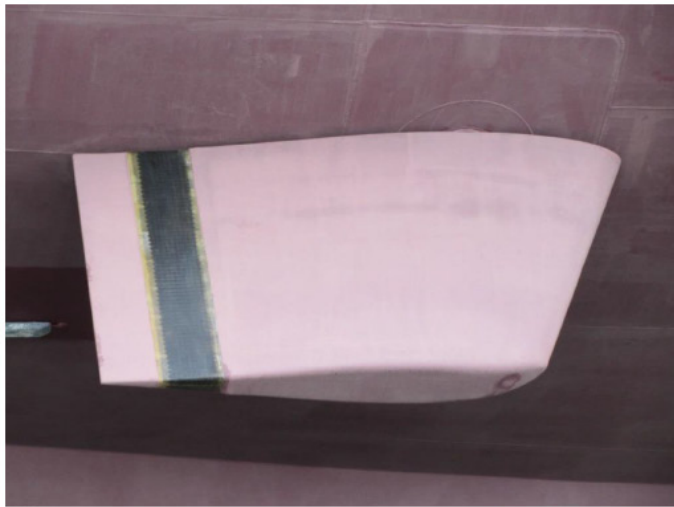
Variant 4



Approaches for skin design

Polyurethan with foam

- Flexible Morphing Trailing Edge
- In-Service since 06/2014 on a marine vessel



Outlook – Main Challenges

- Concentration on conventional high-strain capable materials (GFRP, CRRP) for high acceptance in industrial applications → Structural Design/Good Ideas as enabler for industrial application
- Basic Research in terms of material combinations (GFRP/Elastomers, Compliant Mechanisms, Integration of Functionalities, Hydrophobic Surfaces)
- Manufacturing considerations (complex geometries, cost reduction, material wastage reduction) of these materials e.g. 3D printing of superelastic metals
- Concurrent optimization of skin and substructure kinematics as a whole, integrated system, including energy, weight and stress objectives and/or constraints

